# Continuant Polynomials 

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## Plan

1. Continuant polynomials: definition and interest.
2. Continuants and group of matrices.
3. Leapfrogs and graphs.
4. Generalized Fibonacci polynomials and tilings of strips.
5. General pattern and permanents.

## 1 Continuant polynomials: definition and interest.

$a, b \neq 0$ integers, suppose we have an Euclidean algorithm as follows: $a=b q_{1}+r_{1} ; b=r_{1} q_{2}+r_{2} ; r_{1}=r_{2} q_{3}+r_{3} ; r_{2}=r_{3} q_{4}$ with $\left|r_{i}\right|>\left|r_{i+1}\right|$ We can then write:

$$
\begin{aligned}
& \frac{a}{b}=q_{1}+\frac{r_{1}}{b}=q_{1}+\frac{1}{b / r_{1}} \\
&=q_{1}+\frac{1}{q_{2}+\frac{r_{2}}{r_{1}}}=q_{1}+\frac{1}{q_{2}+\frac{1}{r_{1} / r_{2}}} \\
&=q_{1}+\frac{1}{q_{2}+\frac{1}{q_{3}+\frac{r_{3}}{r_{2}}}} \\
&=q_{1}+\frac{1}{q_{2}+\frac{1}{q_{3}+\frac{1}{q_{4}}}}
\end{aligned}
$$

going backwards we then write:

$$
\frac{a}{b}=q_{1}+\frac{1}{q_{2}+\frac{q_{4}}{q_{3} q_{4}+1}}=q_{1}+\frac{q_{3} q_{4}+1}{q_{2} q_{3} q_{4}+q_{2}+q_{4}}
$$

and finally

$$
\frac{a}{b}=\frac{q_{1} q_{2} q_{3} q_{4}+q_{1} q_{2}+q_{1} q_{4}+q_{3} q_{4}+1}{q_{2} q_{3} q_{4}+q_{2}+q_{4}}
$$

The polynomial appearing on the numerator and denominator are the continuant polynomials.

Very long history...Mainly examples

1. Rafael Bombelli (1530) presented $\sqrt{13}$ as periodic continued fractions.
2. Pietro Cataldi (1548-1626) presented $\sqrt{18}$ as periodic continued fractions.
3. John Wallis (1616-1703) in his book Arithemetica Infinitorium (1655), studied the continued fractions, Euler laid down much of the modern theory (1737). The non commutative settings started as early as Hamilton followed by Wedderburn, P.M. Cohn...

Definition 1.1. Let $X=\left\{t_{1}, t_{2}, \ldots\right\}$ be a countable set of noncommuting variables, and let $\mathbb{Z}\langle X\rangle$ be the free $\mathbb{Z}$-algebra generated by $X$. We define the $n$-th right continuant polynomials

$$
p_{n}\left(t_{1}, \ldots, t_{n}\right) \in \mathbb{Z}\left\langle t_{1}, \ldots, t_{n}\right\rangle \subseteq \mathbb{Z}\langle X\rangle
$$

by $p_{0}=1, p_{1}\left(t_{1}\right)=t_{1}$, and inductively for $i \geq 2$ by

$$
p_{i}\left(t_{1}, \ldots, t_{i}\right)=p_{i-1}\left(t_{1}, \ldots, t_{i-1}\right) t_{i}+p_{i-2}\left(t_{1}, \ldots, t_{i-2}\right) .
$$

the first continuants $p_{n}$. They are

$$
\begin{aligned}
& p_{0}=1, \quad p_{1}=t_{1}, \quad p_{2}=t_{1} t_{2}+1, \quad p_{3}=t_{1} t_{2} t_{3}+t_{1}+t_{3}, \\
& p_{4}=t_{1} t_{2} t_{3} t_{4}+t_{1} t_{2}+t_{1} t_{4}+t_{3} t_{4}+1, \\
& p_{5}=t_{1} t_{2} t_{3} t_{4} t_{5}+t_{1} t_{2} t_{3}+t_{1} t_{2} t_{5}+t_{1} t_{4} t_{5}+t_{3} t_{4} t_{5}+t_{1}+t_{3}+t_{5}
\end{aligned}
$$

They appear, for instance, in:

- Continued fractions
- Generating subgroups of matrices for $M_{2}(R)$ (P.M. Cohn and below).
- Characterizations of comaximal relations in certain rings (P.M. Cohn).
- Characterizations of Euclidean pairs and quasi Euclidean rings (Alahmadi, Jain, Lam, L.).
For $r \in R$ we denote by $P(r)$ the invertible matrix $P(r):=\left(\begin{array}{ll}r & 1 \\ 1 & 0\end{array}\right)$.


## Theorem 1.2.

a) $p_{n}\left(t_{1}, \ldots, t_{n}\right)=t_{1} p_{n-1}\left(t_{2}, \ldots, t_{n}\right)+p_{n-2}\left(t_{3}, \ldots, t_{n}\right)$.
b)

$$
\mathcal{P}_{n}:=P\left(t_{1}\right) P\left(t_{2}\right) \cdots P\left(t_{n}\right)=\left(\begin{array}{cc}
p_{n}\left(t_{1}, \ldots, t_{n}\right) & p_{n-1}\left(t_{1}, \ldots, t_{n-1}\right) \\
p_{n-1}\left(t_{2}, \ldots, t_{n}\right) & p_{n-2}\left(t_{2}, \ldots, t_{n-1}\right)
\end{array}\right)
$$

c) $\mathcal{P}_{n}^{-1}=(-1)^{n}\left(\begin{array}{cc}p\left(t_{n-1}, \ldots, t_{2}\right) & -p\left(t_{n-1}, \ldots, t_{1}\right) \\ -p\left(t_{n}, \ldots, t_{2}\right) & p\left(t_{n}, \ldots, t_{1}\right)\end{array}\right)$

Remark that

- $p_{2 n}$ is a sum of monomials with an even number of factors.
- $p_{2 n+1}$ is a sum of monomials with an odd number of factors.

Put $x_{n}=t_{2 n-1}, y_{n}=t_{2 n}$ and $G_{n}=p_{2 n}, H_{n}=p_{2 n-1}$.
So $G_{n}$ is a polynomial in the indeterminates $x_{1}, y_{1}, \ldots, x_{n}, y_{n}$, and $H_{n}$ is a polynomial in the indeterminates $x_{1}, y_{1}, \ldots, x_{n-1}, x_{n}$.

We have:

$$
\begin{aligned}
& G_{0}=1, \quad G_{1}=x_{1} y_{1}+1, \quad G_{2}=x_{1} y_{1} x_{2} y_{2}+x_{1} y_{1}+x_{1} y_{2}+x_{2} y_{2}+1, \\
& G_{3}=x_{1} y_{1} x_{2} y_{2} x_{3} y_{3}+x_{1} y_{1} x_{2} y_{2}+x_{1} y_{1} x_{2} y_{3}+x_{1} y_{1} x_{3} y_{3}+ \\
& \quad+x_{1} y_{2} x_{3} y_{3}+x_{2} y_{2} x_{3} y_{3}+x_{1} y_{1}+x_{1} y_{2}+x_{1} y_{3}+x_{2} y_{2}+x_{2} y_{3}+x_{3} y_{3}+1
\end{aligned}
$$

and

$$
\begin{aligned}
& H_{0}=0, \quad H_{1}=x_{1}, \quad H_{2}=x_{1} y_{1} x_{2}+x_{1}+x_{2}, \\
& H_{3}=x_{1} y_{1} x_{2} y_{2} x_{3}+x_{1} y_{1} x_{2}+x_{1} y_{1} x_{3}+x_{1} y_{2} x_{3}+x_{2} y_{2} x_{3}+x_{1}+x_{2}+x_{3} .
\end{aligned}
$$

From

$$
P\left(x_{i}\right) P\left(y_{i}\right)=\left(\begin{array}{cc}
x_{i} y_{i}+1 & x_{i} \\
y_{i} & 1
\end{array}\right),
$$

it follows that

$$
\begin{align*}
& \left(\begin{array}{cc}
x_{1} y_{1}+1 & x_{1} \\
y_{1} & 1
\end{array}\right) \cdots\left(\begin{array}{cc}
x_{n} y_{n}+1 & x_{n} \\
y_{n} & 1
\end{array}\right)=  \tag{1.I}\\
& \\
& \left(\begin{array}{cc}
G_{n}\left(x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right) & H_{n}\left(x_{1}, y_{1} \ldots, y_{n-1}, x_{n}\right) \\
H_{n}\left(y_{1}, x_{2}, \ldots, x_{n}, y_{n}\right) & G_{n-1}\left(y_{1}, x_{2}, \ldots, y_{n-1}, x_{n}\right)
\end{array}\right)
\end{align*}
$$

The recursion formulae for $p_{n}$ translate into the following ones between the $G_{n}, H_{n}, x_{n}$ and $y_{n}$ :

$$
\begin{equation*}
G_{n+1}=H_{n+1} y_{n+1}+G_{n} \quad \text { and } \quad H_{n+1}=G_{n} x_{n+1}+H_{n} . \tag{1.II}
\end{equation*}
$$

Using the associativity of the product of matrices we obtain:

$$
\begin{array}{r}
G_{n}\left(x_{1}, \ldots, y_{n}\right)=G_{k}\left(x_{1}, \ldots, x_{k-1}, y_{k}\right) G_{n-k}\left(x_{k+1}, \ldots, y_{n}\right)+ \\
H_{k}\left(x_{1}, \ldots, y_{k-1}, x_{k}\right) H_{n-k}\left(y_{k+1}, x_{k+2} \ldots, y_{n}\right) \tag{1.III}
\end{array}
$$

and
(1.IV)

$$
\begin{array}{r}
H_{n}\left(x_{1}, y_{1}, \ldots, x_{n}\right)=G_{k}\left(x_{1}, \ldots, y_{k}\right) H_{n-k}\left(x_{k}, y-k, \ldots, x_{n}\right)+ \\
H_{k}\left(x_{1}, y_{1}, \ldots, x_{k}\right) G_{n-k-1}\left(y_{n-k}, \ldots, y_{n-1}, x_{n}\right)
\end{array}
$$

Facts:

- All the polynomials $p_{n}, H_{n}$ and $G_{n}$ are sums of monomials with all the coefficients equal to 1 .
- From the defining relations it is easily seen that each $G_{n}$ is a sum of monomials of all possible even degrees $\leq 2 n$ and each $H_{n}$ is a sum of monomials of all possible odd degrees $\leq 2 n-1$.
- Also, the number $m_{n}$ of monomials in $p_{n}$, which is clearly equal to $p_{n}(1,1, \ldots, 1)$, satisfies the relations $m_{0}=1, m_{1}=1, m_{2}=$ $2, m_{n}=m_{n-1}+m_{n-2}$, hence $m_{n}=F_{n+1}$, the $(n+1)$-th Fibonacci number, defined by $F_{0}=0, F_{1}=1$ and $F_{n}=F_{n-1}+F_{n-2}$ for $n \geq 2$.
- The monomials in $H_{n}$ and $G_{n}$ do not contain consecutive letters with descending indexes.
- $\frac{\partial p_{n+1}\left(t_{1}, \ldots, t_{n+1}\right)}{\partial t_{n+1}}=p_{n} ; \quad \frac{\partial G_{n}\left(x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right)}{\partial y_{n}}=H_{n}\left(x_{1}, y_{1}, \ldots, x_{n-1}, x_{n}\right)$


## 2 Continuants and groups of matrices

Let $R$ be any ring, $G L_{2}(R)$ the group of all invertible $2 \times 2$-matrices $E_{2}(R)$ be the elementary group, that is, the subgroup of $G L_{2}(R)$ generated by matrices $\left(\begin{array}{ll}1 & x \\ 0 & 1\end{array}\right)$ and $\left(\begin{array}{ll}1 & 0 \\ y & 1\end{array}\right)$, where $x$ and $y$ range in $R$.

$$
\left(\begin{array}{ll}
1 & x \\
0 & 1
\end{array}\right)^{-1}=\left(\begin{array}{cc}
1 & -x \\
0 & 1
\end{array}\right) \quad \text { and } \quad\left(\begin{array}{ll}
1 & 0 \\
y & 1
\end{array}\right)^{-1}=\left(\begin{array}{cc}
1 & 0 \\
-y & 1
\end{array}\right)
$$

An arbitrary element of $E_{2}(R)$ is a product of finitely many elements of the form

$$
\left(\begin{array}{ll}
1 & x \\
0 & 1
\end{array}\right)\left(\begin{array}{ll}
1 & 0 \\
y & 1
\end{array}\right)=\left(\begin{array}{cc}
x y+1 & x \\
y & 1
\end{array}\right) .
$$

These are exactly the factors on the left in the equation (1.I). Thus an arbitrary element of $E_{2}(R)$ is a matrix of the form

$$
\left(\begin{array}{cc}
G_{n}\left(x_{1}, y_{1}, \ldots, x_{n}, y_{n}\right) & H_{n}\left(x_{1}, y_{1} \ldots, y_{n-1}, x_{n}\right) \\
H_{n}\left(y_{1}, x_{2}, \ldots, x_{n}, y_{n}\right) & G_{n-1}\left(y_{1}, x_{2}, \ldots, y_{n-1}, x_{n}\right)
\end{array}\right),
$$

with $x_{1}, y_{1}, \ldots, x_{n}, y_{n} \in R$.
Let $G$ be the subsemigroup of the multiplicative semigroup $M_{2}(R)$ generated by all matrices of type

$$
P(x):=\left(\begin{array}{ll}
x & 1 \\
1 & 0
\end{array}\right),
$$

where $x$ ranges in $R$. As Cohn proved in 1966, the semigroup $G$, set of all products $P\left(x_{1}\right) \cdots P\left(x_{n}\right)$ with $n \geq 1$ and $x_{1}, \ldots, x_{n} \in R$, is a group, because $P(0)^{2}$ is the identity of $G L_{2}(R)$ and $P(x)^{-1}=$ $P(0) P(-x) P(0)$.

Theorem 2.1. For any ring $R$, exactly one of the following two conditions holds:
(a) Either $G=E_{2}(R)$, or
(b) The group $G$ is the semidirect product $E_{2}(R) \rtimes C$ of the group $E_{2}(R)$ and the cyclic group $C$ of order 2 generated by the involution $P(0)=\left(\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right)$.

The action of $P(0)$ on $E_{2}(R)$ is given by

$$
\left(\begin{array}{ll}
1 & x \\
0 & 1
\end{array}\right) \mapsto P(0)\left(\begin{array}{ll}
1 & x \\
0 & 1
\end{array}\right) P(0)=\left(\begin{array}{ll}
1 & 0 \\
x & 1
\end{array}\right)
$$

and

$$
\left(\begin{array}{ll}
1 & 0 \\
y & 1
\end{array}\right) \mapsto P(0)\left(\begin{array}{ll}
1 & 0 \\
y & 1
\end{array}\right) P(0)=\left(\begin{array}{ll}
1 & y \\
0 & 1
\end{array}\right) .
$$

## 3 Leapfrogs and graphs

First leapfrog construction
$0)$ The first term of $p_{n}$ is $t_{1} t_{2} \cdots t_{n}$.

1) The next terms are obtained by erasing two consecutive indeterminates (the frog jumps over them) from $t_{1} t_{2} \cdots t_{n}$ to get the sum: $t_{3} t_{4} \cdots t_{n}+t_{1} t_{4} t_{5} \cdots t_{n}+t_{1} t_{2} t_{5} \cdots t_{n}+\ldots$
2) We erase 2 pairs of consecutive indeterminates (2 jumps) and get the terms

$$
\sum_{1 \leq i_{1}<i_{2}-1 \leq n} t_{1} \cdots \widehat{t_{i_{1}}} \widehat{t_{i_{1}+1}} \cdots \widehat{t_{i_{2}}} \widehat{t_{i_{2}+1}} \cdots t_{n}
$$

3) We then continue adding terms corresponding to 3 leaps, 4 leaps, and so on. Finally, we can write

$$
p_{n}\left(t_{1}, \ldots, t_{n}\right)=\sum_{i_{1}, i_{2}, \ldots, i_{j}} t_{1} \cdots \widehat{t_{i_{1}}} \widehat{t_{i_{1}+1}} \cdots \widehat{t_{i_{2}}} \widehat{t_{i_{2}+1}} \cdots \widehat{t_{i_{j}}} \widehat{t_{i_{j}+1}} \cdots t_{n}
$$

where $1 \leq j \leq\lfloor n / 2\rfloor$ and $i_{j}+1<i_{j+1}$ for every $j$,

Graph and second leapfrog construction
Consider the directed graph (quiver) $\Gamma_{n}$ with two vertices $A$ and $B$ :


Thus $\Gamma_{n}$ has $2 n$ arrows, of which $n$ goes from $A$ to $B$ and are indexed by the indeterminates $x_{i}$, and $n$ from $B$ to $A$ indexed by the indeterminates $y_{i}$.

The facts mentioned earlier about the polynomials $G_{n}$ and $H_{n}$ motivate the definition of the ideal $I$ in the construction below.
Let $k$ be a field, consider the quiver algebra $k \Gamma_{n}$ and the ideal $I$ of $k \Gamma_{n}$ generated by all paths $x_{i} y_{j}: A \xrightarrow{x_{i}} B \xrightarrow{y_{j}} A$ with $i>j$ and all paths $y_{i} x_{j}: B \xrightarrow{y_{i}} A \xrightarrow{x_{j}} B$ with $i \geq j$.

Theorem 3.1. Let $R=k \Gamma_{n} / I$.

1) The $k$-algebra $R$ is finite dimensional.
2) $J(R)$ is a nilpotent ideal that contains all nilpotent elements of $R$.
3) $R=R_{0} \oplus R_{1}$ is 2-graded, where $R_{0}$ corresponds to the paths of even length and $R_{1}$ to the paths of odd length.
4) The images of the polynomials $G_{n}$ in $R$ are in $R_{0}$ and the images of the polynomials $H_{n}$ are in $R_{1}$.
5) 

$H_{n}=\left(1-\sum_{1 \leq i \leq j \leq n} x_{i} y_{j}\right)^{-1}\left(\sum_{i=1} x_{i}\right) \quad$ and $\quad G_{n}=\left(1-\sum_{1 \leq i \leq j \leq n} x_{i} y_{j}\right)^{-1}$
for every $n \geq 0$.

## 4 Generalized Fibonacci Polynomials and tiling of strips

Definition 4.1. The polynomials $f_{n} \in \mathbb{Z}\left\langle x_{1}, y_{1}, x_{2}, y_{2}, \ldots,\right\rangle$ are defined by the recursion formulae:

$$
\begin{align*}
& f_{-1}=0, \quad f_{0}=1,  \tag{4.I}\\
& f_{n}\left(x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right)=\begin{aligned}
& f_{n-1}\left(x_{1}, \ldots, x_{n-1}, y_{1}, \ldots, y_{n-1}\right) x_{n}+ \\
&+f_{n-2}\left(x_{1}, \ldots, x_{n-2}, y_{1}, \ldots, y_{n-2}\right) y_{n} .
\end{aligned}
\end{align*}
$$

The first of these polynomials $f_{n}$ are

$$
\begin{aligned}
& f_{0}=1, \quad f_{1}=x_{1}, \quad f_{2}=x_{1} x_{2}+y_{2}, \\
& f_{3}=x_{1} x_{2} x_{3}+x_{1} y_{3}+y_{2} x_{3}, \\
& f_{4}=x_{1} x_{2} x_{3} x_{4}+x_{1} x_{2} y_{4}+x_{1} y_{3} x_{4}+y_{2} x_{3} x_{4}+y_{2} y_{4}, \\
& f_{5}=x_{1} x_{2} x_{3} x_{4} x_{5}+x_{1} x_{2} x_{3} y_{5}+x_{1} x_{2} y_{4} x_{5}+x_{1} y_{3} x_{4} x_{5}+ \\
& \quad \quad+x_{1} y_{3} y_{5}+y_{2} x_{3} x_{4} x_{5}+y_{2} x_{3} y_{5}+y_{2} y_{4} x_{5}, \ldots
\end{aligned}
$$

- The number of monomials in each $f_{n}$ is the $(n+1)$-th Fibonacci number $F_{n+1}$.
- When we specialize all the indeterminates $y_{i}$ to 1 , we get back the continuant polynomials i.e. $f_{n}\left(x_{1}, \ldots, x_{n}, 1, \ldots, 1\right)=p_{n}\left(x, \ldots, x_{n}\right)$.
- If we specialize further: $f_{n}(x, \ldots, x, 1,1, \ldots, 1)=F_{n}(x)$, i.e. we get the commutative Fibonacci polynomials.
- The polynomials $f_{n}$ are homogeneous of degree $n$ if we give the $x_{i}$ degree one and the $y_{i}$ degree 2 .
- Notice that the indeterminate $y_{1}$ does not appear in any polynomial $f_{n}\left(x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right)$.

Theorem 4.2. 1. $f_{n}(2,2, \ldots, 2,-1,-1, \ldots,-1)=n$
2. $f_{n}(x+1, x+1, \ldots, x+1,-x,-x, \ldots,-x)=1+x+x^{2}+\cdots+x^{n-1}$.
3. We have:

$$
\begin{aligned}
& \mathcal{F}_{n}:=\left(\begin{array}{ll}
x_{1} & 1 \\
y_{1} & 0
\end{array}\right) \cdots\left(\begin{array}{cc}
x_{n} & 1 \\
y_{n} & 0
\end{array}\right)= \\
& =\left(\begin{array}{cc}
f_{n}\left(x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right) & f_{n-1}\left(x_{1}, \ldots, x_{n-1}, y_{1}, \ldots, y_{n-1}\right) \\
y_{1} f_{n-1}\left(x_{2}, \ldots, x_{n}, y_{2}, \ldots, y_{n}\right) & y_{1} f_{n-2}\left(x_{2}, \ldots, x_{n-1}, y_{2}, \ldots, y_{n-1}\right)
\end{array}\right) .
\end{aligned}
$$

4. 

$$
\begin{aligned}
\mathcal{F}_{n}= & \left(\begin{array}{cc}
f_{k}\left(x_{1}, \ldots, y_{k}\right) & f_{k-1}\left(x_{1}, \ldots, y_{k-1}\right) \\
y_{1} f_{k-1}\left(x_{2}, \ldots, y_{k}\right) & y_{1} f_{k-2}\left(x_{2}, \ldots, y_{k-1}\right)
\end{array}\right) . \\
& \cdot\left(\begin{array}{cc}
f_{n-k}\left(x_{k+1}, \ldots, y_{n}\right) & f_{n-k-1}\left(x_{k+1}, \ldots, y_{n-1}\right) \\
y_{k+1} f_{n-k-1}\left(x_{k+2}, \ldots, y_{n}\right) & y_{k+1} f_{n-k-2}\left(x_{k+2}, \ldots, y_{n-1}\right)
\end{array}\right)
\end{aligned}
$$

5. $f_{n}\left(x_{1}, \ldots, x_{n}, y_{1}, x_{1} x_{2}, x_{2} x_{3}, x_{3} x_{4}, \ldots, x_{n-1} x_{n}\right)=F_{n+1} x_{1} x_{2} \ldots x_{n}$.
6. $f_{n}\left(x_{1}, \ldots, y_{n}\right)=f_{k}\left(x_{1}, \ldots, y_{k}\right) f_{n-k}\left(x_{k+1}, \ldots, y_{n}\right)+$ $+f_{k-1}\left(x_{1}, \ldots, y_{k-1}\right) y_{k+1} f_{n-k-1}\left(x_{k+2}, \ldots, y_{n}\right)$
7. $f_{n}\left(x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right)=$

$$
=x_{1} f_{n-1}\left(x_{2}, \ldots, x_{n}, y_{2}, \ldots, y_{n}\right)+y_{2} f_{n-2}\left(x_{3}, \ldots, x_{n}, y_{3}, \ldots, y_{n}\right) .
$$

8. $f_{n}\left(x_{1}, x_{2}, \ldots, y_{n}\right)=$
$=f_{k+1}\left(x_{1}, \ldots, x_{k}, f_{n-k}\left(x_{k+1}, \ldots, y_{n}\right), y_{1}, \ldots, y_{k}, f_{n-k-1}\left(x_{k+2}, \ldots, y_{n}\right)\right)$.
9. $\frac{\partial f_{n}\left(x_{1}, \ldots, y_{n}\right)}{\partial x_{k}}=f_{k-1}\left(x_{1}, \ldots, y_{k-1}\right) f_{n-k}\left(x_{k+1}, \ldots, y_{n}\right)$, for $1 \leq k \leq n$. $\frac{\partial f_{n}\left(x_{1}, \ldots, y_{n}\right)}{\partial y_{k}}=f_{k-2}\left(x_{1}, \ldots, y_{k-2}\right) f_{n-k}\left(x_{k+1}, \ldots, y_{n}\right)$, for $2 \leq k \leq n$.

It is also possible to describe the generalized Fibonacci polynomials via leapfrog constructions and a path algebra can also be defined based on this definition.

Definition 4.3. A linear tiling of a row of squares (a $1 \times n$ strip of square cells) is a covering of the strip of squares with squares and dominos (which cover two squares).

For instance, the polynomial $f_{3}=x_{1} x_{2} x_{3}+x_{1} y_{3}+y_{2} x_{3}$ parametrizes the set of the three linear tilings

of a row of three squares. Here $x_{i}$ denotes the $i$-th square and $y_{i}$ denotes the domino that covers the $(i-1)$-th and the $i$-th square (the domino that "ends on the $i$-th square".) The Fibonacci number $F_{n}$ represents the number of tilings of a strip of length $n$ using length 1 squares and length 2 dominos.

## 5 General pattern and permanents.

Now consider the following family of polynomials $g_{n}$, with $n \geq 0$. To define them, we need countably many non-commutative indeterminates $x_{i j}$, where $1 \leq i \leq j$. Set $g_{0}=1$ and

$$
\begin{equation*}
g_{n}=\sum_{i=1}^{n} g_{i-1} x_{i n}, \quad \text { for } \quad n \geq 1 \tag{5.I}
\end{equation*}
$$

For instance, the first polynomials $g_{n}$ are

$$
\begin{aligned}
& g_{1}=x_{11}, \quad g_{2}=x_{12}+x_{11} x_{22}, \quad g_{3}=x_{13}+x_{11} x_{23}+x_{12} x_{33}+x_{11} x_{22} x_{33}, \\
& g_{4}=x_{14}+x_{11} x_{24}+x_{12} x_{34}+x_{11} x_{22} x_{34}+x_{13} x_{44}+x_{11} x_{23} x_{44}+ \\
& \quad+x_{12} x_{33} x_{44}+x_{11} x_{22} x_{33} x_{44} .
\end{aligned}
$$

For every $n \geq 1$, the polynomial $g_{n} \in \mathbb{Z}\left\langle x_{i j} \mid 1 \leq i \leq j \leq n\right\rangle$. The polynomial $g_{n}$ is a sum of monic monomials that parametrize all linear tilings of a strip of $n$ square cells, that is, all coverings of the strip of
squares with rectangles of any length $1,2, \ldots, n$. The indeterminate $x_{i j}$ indicates the rectangle of length $j-i+1$ that starts from the $i$-th square and ends covering the $j$-th square.

For instance, $g_{3}=x_{13}+x_{11} x_{23}+x_{12} x_{33}+x_{11} x_{22} x_{33}$ and, correspondingly, the tilings of a strip of three squares are


We can get back the polynomials $p_{n}$ and $f_{n}$ by different specializations.

We have:

$$
\left(g_{1}, \ldots, g_{n}\right)=\left(g_{0}, \ldots, g_{n-1}\right)\left(\begin{array}{cccc}
x_{11} & x_{12} & \ldots & x_{1 n} \\
0 & x_{22} & \ldots & x_{2 n} \\
\vdots & \ddots & \ddots & \vdots \\
0 & \ldots & 0 & x_{n n}
\end{array}\right)
$$

Since, for $1 \leq l \leq n$, a tiling of a strip of length $n$ is obtained by a tile of length $l$ followed by a tiling of length $n-l$, the following formula, where we have specified explicitly the indeterminates ("the tiles") for each polynomial, is easy to get:

$$
g_{n}\left(x_{i j} ; 1 \leq i \leq j \leq n\right)=\sum_{l=1}^{n} x_{11} g_{n-l}\left(x_{l+i, l+j} ; 1 \leq i \leq j \leq n-l\right)
$$

$R$ a ring, define a mapping perm: $M_{n}(R) \rightarrow R$ setting, for every matrix $A=\left(a_{i, j}\right)_{i, j} \in M_{n}(R)$,

$$
\operatorname{perm}(A):=\sum_{\sigma \in S_{n}} a_{1, \sigma(1)} \ldots a_{n, \sigma(n)} .
$$

If $A_{i, j}$ denotes the $(n-1) \times(n-1)$-matrix that results from $A$ removing the $i$-th row and the $j$-th column, then $\operatorname{perm}(A):=\sum_{j=1}^{n} a_{1, j} \operatorname{perm}\left(A_{1, j}\right)=$ $\sum_{j=1}^{n} \operatorname{perm}\left(A_{n, j}\right) a_{n, j}$ (it is possible to expand our permanent along the first row or the last row only).

Theorem 5.1. For every $n \geq 1$, we have:

$$
g_{n}\left(x_{i j}\right)=\operatorname{perm}\left(A_{n}\right)=\operatorname{perm}\left(A_{n}^{t}\right),
$$

where

$$
A_{n}=\left(\begin{array}{ccccc}
x_{11} & x_{12} & x_{13} & \ldots & x_{1 n} \\
1 & x_{22} & x_{23} & \ldots & x_{2 n} \\
0 & 1 & x_{33} & \ddots & x_{3 n} \\
\vdots & \ddots & \ddots & \ddots & \vdots \\
0 & \ldots & 0 & 1 & x_{n n}
\end{array}\right)
$$

## THANK YOU!

